Bhubanananda Orissa School of Engineering Lesson Plan

Discipline:	Semester:6th	Name of the Teaching Faculty: Pradeep Kumar Dhal Samant,
ETC	N. CD /	Lecturer in ETC Semester from 10.03.2022 to 10.06.2022
Subject: CONTROL SYSTEMS & COMPONENT	No of Days/per week class allotted: 4 (Mon, Tues, Thurs & Friday)	No of weeks: 14
Week No.	Class Day	Theory Topics
181	10-03-2022	Unit 1. Fundamental of Control System 1.1 Classification of Control system 1.2 Open loop system & Closed loop system and its comparison
	11-03-2022	1.3 Effects of Feed back1.4 Standard test Signals (Step, Ramp, Parabolic, Impulse Functions)
2 nd	14-03-2022	1.5 Servomechanism 1.6 Regulators (Regulating systems)
	15-03-2022	Unit 2. Transfer Functions 2.1 Transfer Function of a system & Impulse response.
	17-03-2022	2.2 Properties, advantages & disadvantages of Transfer function.
3 rd	21-03-2022	2.3 Poles & zeroes of Transfer function.2.4 Representation of poles & Zero on the s-plane.
	22-03-2022	2.5 Simple problems of transfer function of network.
	24-03-2022	Unit 3. Control system Components & mathematical modelling of physical system 3.1 Components of Control System 3.2 Potentiometer, Diode modulator & demodulator
	25-03-2022	3.2 Synchros
4 th	28-03-2022	3.3 DC motors, AC Servomotors
	29-03-2022	3.4 Modelling of Electrical Systems (R, L, C, Analogous systems)
	31-03-2022	Unit 4. Block Diagram & Signal Flow Graphs (SFG) 4.1 Definition of Basic Elements of a Block Diagram 4.2 Canonical Form of Closed loop Systems
5 th	04-04-2022	4.3 Rules for Block diagram Reduction
	05-04-2022	4.4 Procedure for of Reduction of Block Diagram
	07-04-2022	4.5 Simple Problem for equivalent transfer function
	08-04-2022	4.6 Basic Definition in SFG & properties 4.7 Mason's Gain formula
6 th	11-04-2022	4.8 Steps for solving Signal flow Graph
	12-04-2022	4.9 Simple problems in Signal flow graph for network

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		CLASS TEST 1
7 th	18-04-2022	Unit 5. Time Domain Analysis of Control Systems 5.1 Definition of Time, Stability, steady-state response, accuracy, transient accuracy, in-sensitivity and robustness.
	19-04-2022	5.2 System Time Response
	21-04-2022	5.3 Analysis of Steady State Error
	22-04-2022	5.4 Types of Input & Steady state Error (Step)
8 th	25-04-2022	5.4 Steady state Error (Ramp, Parabolic)
	26-04-2022	5.5 Parameters of first order system & second-order systems
	28-04-2022	5.6 Derivation of time response Specification (Delay time, Rise time Peak time, Setting time, Peak over shoot)
o th	29-04-2022	Unit 6. Feedback Characteristics of Control Systems 6.1 Effect of parameter variation in open loop & closed loop systems
9 th	02-05-2022	6.2 Introduction to Basic control action & basic modes of feedback control (proportional, integral & derivative).
	05-05-2022	6.3 Effect of feedback on overall gain and stability.
	06-05-2022	6.4 Realisation of controller (P, PI) with OPAMP
10 th	09-05-2022	6.4 Realisation of controller (PD, PID) with OPAMP
	10-05-2022	1st Internal Assessment
11 th	12-05-2022	Unit 7. Stability concept & Root locus Method 7.1 Effect of location of poles on stability
	13-05-2022	7.2 Routh Hurwitz stability criterion
	17-05-2022	7.3 Steps for Root locus method
	19-05-2022	7.4 Root locus method of design (Simple problem)
	20-05-2022	7.4 Root locus method of design (Simple problem) Class Test II
12 th	23-05-2022	Unit 8. Frequency-response analysis &Bode Plot 8.1 Frequency response, Relationship between time & frequency response 8.2 Methods of Frequency response
	24-05-2022	8.3 Polar plots & steps for polar plot, simple problems
	26-05-2022	8.4 Bodes plot & steps for Bode plots
	27-05-2022	8.4 Bodes plot & steps for Bode plots, simple problems

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13 th	31-05-2022	8.5 Stability in frequency domain, Gain Margin & Phase margin
	02-06-2022	8.6 Nyquist plots. Nyquist stability criterion
	03-06-2022	8.7 Simple problems as above
14 th	06-06-2022	Unit 9. State variable Analysis 9.1 Concepts of state, state variable, state model
	07-06-2022	9.2 State models for linear continuous time functions (simple)
	09-06-2022	2 nd Internal Assessment
	10-06-2022	OVERALL REVISION

HOD (E&TC)

ACADEMIC COORDINATOR

Principal